

# Convergence to Consensus in Multiagent Systems

**Setup:**  $N$  agents, agent  $i \in \{1, \dots, N\}$  has initial opinion  $x_i(1) \in \mathbb{R}$ ,  $x(1) \in \mathbb{R}^N$  is initial opinion profile  
**Question:** Do agents converge to a consensus when repeatedly confronted with the opinions of others?

## Mathematical Conditions

**Behavioral Model** Agent  $i$  gets information of some other agents' opinions and takes a **weighted average**. Network topology of information exchange and weighting may change over time or may be a function of the opinion landscape. Implies systems dynamics as:

$$x(t+1) = A(t)x(t) = A(t) \cdots A(2)A(1)x(1)$$

with  $A(t)$  row-stochastic (implements weighted averaging).

### Mathematical Questions

- $\lim_{t \rightarrow \infty} A(t) \cdots A(2)A(1) = A(\infty, 1)$  exists?
- $A(\infty, 1)$  consensus matrix (all rows equal)?

## Results

**Result 0.** When (I) holds there is  $0 < t_1 < t_2 < \dots$  such that  $A(t_s - 1) \cdots A(t_{s-1}) =: A(t_s, t_{s-1})$  have **same zero pattern**

$$\dots \simeq A(t_s, t_{s-1}) \simeq \dots \simeq A(t_3, t_2) \simeq A(t_2, t_1).$$

### Conditions

- Self-confidence**  $A(t)$  has positive diagonal
- Positive weights uniformly bounded** from below. There is  $\delta > 0$  such that for all  $t$ ,  $\min_{\{ij \mid a_{ij}(t) > 0\}} a_{ij}(t) > \delta$
- Mutual confidence**  $A(t) \simeq A(t)^T$
- Bounded lengths of intercommunication intervals.** There are  $T_1, T_2 > 0$  such that for all  $s$  it holds,  $t_s - t_{s-1} < T_1 + T_2 \log(s)$  and  $T_2 \leq -\frac{1}{\log \delta}$ . (Slow growth allowed!)
- $A(t_s, t_{s-1})$  has **only one connected cluster without outlinks**.

### Result 1. Opinions converge

- if (I), (II), (III); or
- only in connected clusters without outlinks, if (I), (II), (IV).

### Result 2. Opinions converge to consensus

- if (I), (II), (III), (V), or
- if (I), (II), (IV), (V).

**Consider  $A(t)$  is a function of  $x(t)$ ?** Conditions (I), (II), (III) might be easy to check for the function, but (IV) and (V) are conditions on accumulations of matrices of unknown length and thus very difficult to check!

## References

- Lorenz, J. **Repeated Averaging and Bounded Confidence** (2007) Doctoral Thesis, Universität Bremen  
 Lorenz, J. **A stabilization theorem for dynamics of continuous opinions** (2005) Physica A, 355(1), 217–223

Jan Lorenz, [www.janlo.de](http://www.janlo.de)

## Human Behavior

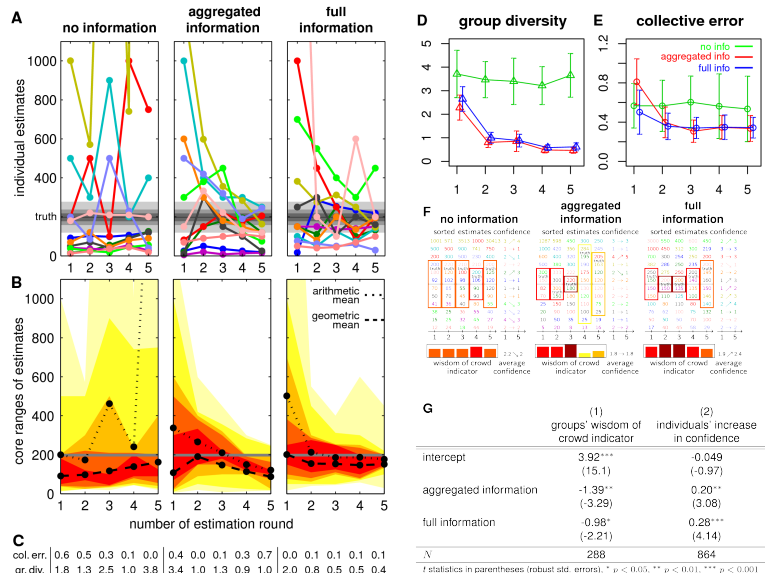
**Experimental Setup:**  $N = 12$  humans in a computer laboratory  
 12 experimental sessions, **6 estimation tasks**, e.g. "How many murders were registered in Switzerland 2006?"  
**5 rounds** of estimation (truth unknown to agents)  
**Payment** for each estimate when low deviation to truth  
 3 conditions of information propagation after each round:

- no information** answer five times the same question
  - aggregated information** receive the arithmetic mean of all 12 estimates
  - full information** receive graphics of trajectories and list of all estimates
- ±10% → 4 points  
 ±20% → 2 points  
 ±40% → 1 point  
 else → 0 points

### Experimental Questions

- Do agents converge through information feedback?
- Does information feedback has an impact on the wisdom of crowds effect?**

## Results



**Result 1.** Convergence but **not towards a full consensus**. Reason: Agents belief in "Others also don't know." this implies some random fluctuation as under the "no info" condition.

**Result 2.** Impact of Information Feedback:  
**Social Influence Effect** Diversity of estimates diminishes without lowering collective error. (A,B,C; Stats: D,E)  
**Range Reduction Effect** Position of truth drops out of range of estimates (or to periphery). (F; Stats: G)  
**Confidence Effect** Agents become more confident. Danger of extrapolation to crowd! (F; Stats: G)

## Reference

J. Lorenz, H. Rauhut, F. Schweitzer, D. Helbing. **How social influence can undermine the wisdom of crowd effect** (May 2011) PNAS